

Math 1433

11 December 2023

Warm-up:

For which values of p does

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - p I_{2 \times 2}$$

have an inverse?

Any system of linear equations can be represented as a matrix equation

$$A\vec{x} = \vec{b}.$$

If A^{-1} exists, then

$$\vec{x} = A^{-1}\vec{b}$$

is the unique solution to the system.

But what if A^{-1} doesn't exist?

- This could be because number of variables \neq number of equations.
- This could be because $\det(A) = 0$.

Last
Time

The Rouché–Capelli Theorem

The system $A\vec{x} = \vec{b}$ has at least one solution
if and only if $\text{rank}(A) = \text{rank}([A \ \vec{b}])$.

Reminder: A is the “coefficient matrix”, and $[A \ \vec{b}]$ is the “augmented matrix”.

If there are any solutions, the collection of all solutions has dimension $n - \text{rank}(A)$, where n is the number of variables.

Dimension:

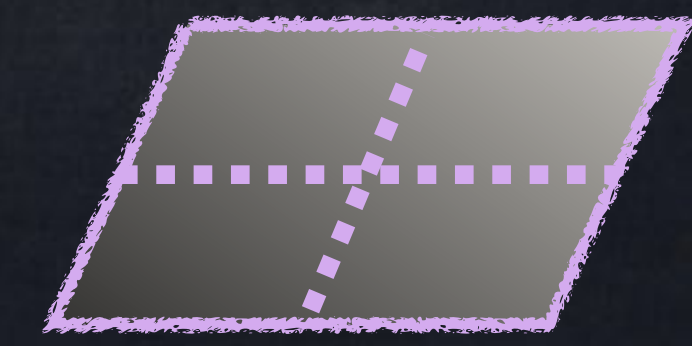
0



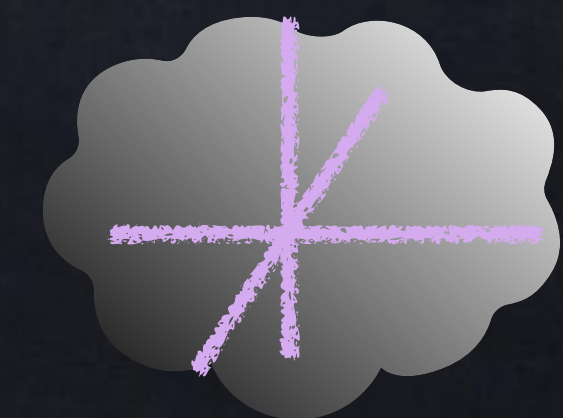
1



2



3



The matrix

$$A = \begin{bmatrix} 5 & 2 & 7 \\ 1 & 0 & 1 \\ 12 & 7 & 19 \end{bmatrix}$$

has determinant 0 (and rank 2, which we calculated last week).

What does that mean for $A\vec{x} = \vec{b}$?

Rank/system examples

Last
time

Ex 2.

$$\begin{cases} 5x + 2y + 7z = 6 \\ x + z = 4 \\ 12x + 7y + 19z = 9 \end{cases}$$

$$A = \begin{bmatrix} 5 & 2 & 7 \\ 1 & 0 & 1 \\ 12 & 7 & 19 \end{bmatrix}$$

$$\begin{aligned} \text{rank}(A) &= 2 \\ \text{rank}(A|\vec{b}) &= 3 \end{aligned}$$

$$[A \vec{b}] = \left[\begin{array}{ccc|c} 5 & 2 & 7 & 6 \\ 1 & 0 & 1 & 4 \\ 12 & 7 & 19 & 9 \end{array} \right]$$

The coefficient and augmented matrices have different ranks, so there are no solutions to the system.

Rank/system examples

Last
time

Ex 3.

$$\begin{cases} 5x + 2y + 7z = \underline{10} \\ x + z = \underline{4} \\ 12x + 7y + 19z = \underline{13} \end{cases}$$

$$A = \begin{bmatrix} 5 & 2 & 7 \\ 1 & 0 & 1 \\ 12 & 7 & 19 \end{bmatrix}$$

$$\begin{aligned} \text{rank}(A) &= 2 \\ \text{rank}(A|b) &= 2 \end{aligned}$$

$$[A \vec{b}] = \left[\begin{array}{ccc|c} 5 & 2 & 7 & \underline{10} \\ 1 & 0 & 1 & \underline{4} \\ 12 & 7 & 19 & \underline{13} \end{array} \right]$$

The coeff. and augmented matrices have the same rank, so the system does have at least one solution. The space of all solutions has dimension

(# of variables) - (rank of A) = 3 - 2 = 1,
so the set of solutions is a LINE in 3D space.

Free variables

How can we describe the solutions nicely when there are infinitely many?

A **free variable** is a variable whose value can be set to anything when describing solutions to a system.

- If $n - \text{rank}(A) = d$, we have d free variables.
- We can choose which of the variables are free.

Free variables

Ex 3 again

$$\begin{cases} 5x + 2y + 7z = 10 \\ x + z = 4 \\ 12x + 7y + 19z = 13 \end{cases}$$

$$\text{rank}(A) = 2$$

$$\text{rank}(A|b) = 2$$

$$(\# \text{ of vars.}) - \text{rank}(A) = 1$$

We know we have exactly one free variable.

We can pick any one of x or y or z for that variable.

With x free, all solutions look like $(x, x-9, 4-x)$

With y free: $(x, y, z) = (y+9, y, -y-5)$

With z free: $(x, y, z) = (4-z, -5-z, z)$

Rank and determinant

$$\begin{cases} 5x + 2y + 7z = 6 \\ x + z = 4 \\ 12x + 7y + 18z = 9 \end{cases} \quad A = \begin{bmatrix} 5 & 2 & 7 \\ 1 & 0 & 1 \\ 12 & 7 & 18 \end{bmatrix} \quad \begin{array}{l} \det(A) \neq 0 \\ \text{rank}(A) = 3 \\ n - \text{rank}(A) = 0 \end{array}$$

$$\begin{cases} 5x + 2y + 7z = 6 \\ x + z = 4 \\ 12x + 7y + 19z = 9 \end{cases} \quad A = \begin{bmatrix} 5 & 2 & 7 \\ 1 & 0 & 1 \\ 12 & 7 & 19 \end{bmatrix} \quad \begin{array}{l} \det(A) = 0 \\ \text{rank}(A) = 2 \end{array}$$
$$\begin{cases} 5x + 2y + 7z = 10 \\ x + z = 4 \\ 12x + 7y + 19z = 13 \end{cases}$$

For an $n \times n$ matrix A , $\det(A) = 0$ if and only if $\text{rank}(A) < n$.

Right-hand side zeros

What can we say about a square system $A\vec{x} = \vec{0}$ where the right-side has only zeros?

$$\begin{cases} 5x + \quad \quad z = 0 \\ 2x + 2y + 3z = 0 \\ -8x + 2y + \quad z = 0 \end{cases}$$

- $(x, y, z) = (0, 0, 0)$ is a solution.
- In order to have any *other* solutions, the coefficient matrix must have a determinant of 0 (because if not then we could solve $\vec{x} = A^{-1}\vec{0} = \vec{0}$).
- In that case there will be infinitely many solutions.
The set of all solutions will form a line or a plane in 3D space.

Systems of equations appear in many kinds of tasks.

They are not always in the format $\begin{cases} _x + _y = _ \\ _x + _y = _ \end{cases}$.

Task: Describe *all* vectors $\vec{v} = \begin{bmatrix} x \\ y \end{bmatrix}$ for which $\begin{bmatrix} 6 & 4 \\ 1 & 3 \end{bmatrix} \vec{v} = 7 \vec{v}$.

Using y as a free variable, $\begin{bmatrix} 4y \\ y \end{bmatrix}$ for any y .

In other words, these are all the multiples of $[4, 1]$.

Eigenvectors and eigenvalues

For a square matrix A , if we have

$$A\vec{v} = s\vec{v}$$

for some number s and some vector $\vec{v} \neq \vec{0}$ then

- the vector \vec{v} is called an **eigenvector** of A , and
- the number s is called an **eigenvalue** of A .

Note that if \vec{v} is an eigenvector, any scalar multiple of \vec{v} will also be an eigenvector.

Eigenvectors and eigenvalues

We just saw that

$$\begin{bmatrix} 6 & 4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix} = 7 \begin{bmatrix} 4 \\ 1 \end{bmatrix}.$$

Using this new vocabulary, we can say that

- $[4, 1]$ is an eigenvector of $\begin{bmatrix} 6 & 4 \\ 1 & 3 \end{bmatrix}$.
- 7 is an eigenvalue of $\begin{bmatrix} 6 & 4 \\ 1 & 3 \end{bmatrix}$.

If you know an eigenvalue of a matrix, the method we already used is how you find eigenvectors.

But how do you find eigenvalues?

Example: Find the eigenvalues of $\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix}$.

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = s \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} 1-s & 2 \\ 3 & 2-s \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

If $\det\begin{pmatrix} 1-s & 2 \\ 3 & 2-s \end{pmatrix} \neq 0$ then this has exactly 1 solution (which will be $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$). If $\det\begin{pmatrix} 1-s & 2 \\ 3 & 2-s \end{pmatrix} = 0$ then this has ∞ solutions.

We want

$$(1-s)(2-s) - (2)(3) = 0.$$

So the eigenvalues are $s = -1$ and $s = 4$.

Warm-up:

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - p I_{2 \times 2}$$

$$\det(A - pI) = 0$$

if $p = -1, p = 4$

Finding eigenvalues

The eigenvalues of A are the values of s for which $\det(A - sI) = 0$.

Proof: if $A\vec{v} = s\vec{v}$ and $\vec{v} \neq \vec{0}$ then

$$A\vec{v} = I(s\vec{v})$$

$$A\vec{v} - Is\vec{v} = \vec{0}$$

$$(A - Is)\vec{v} = \vec{0} \quad \text{with } \vec{v} \neq \vec{0}$$

$$\det(A - Is) = 0$$

Finding eigenvalues

The eigenvalues of A are the values of λ for which $\det(A - \lambda I) = 0$.

In most book/websites, the Greek lowercase lambda λ is used for eigenvalues.

Determinants and eigenvalues are also related in the following way:

If $\lambda_1, \dots, \lambda_n$ are the eigenvalues of A (counted with algebraic multiplicity*), then

$$\det(A) = \lambda_1 \times \lambda_2 \times \dots \times \lambda_n.$$

* We will define this in January.

For an $n \times n$ matrix A , either...

ALL of these are true:

- A is invertible
- $\det(A) \neq 0$
- 0 is not an eigenvalue
- $\text{rank}(A) = n$

or

ALL of these are true:

- A is non-invertible
- $\det(A) = 0$
- 0 is an eigenvalue
- $\text{rank}(A) < n$

Task: Find the eigenvalues of $A = \begin{bmatrix} 3 & 10 \\ 1 & 5 \end{bmatrix}$.

Solving $(3 - \lambda)(5 - \lambda) - (10)(1) = 0$

gives $\lambda_1 = 4 + \sqrt{11}$ and $\lambda_2 = 4 - \sqrt{11}$.

Task: Find the eigenvalues of $A = \begin{bmatrix} 2 & -10 \\ 1 & 8 \end{bmatrix}$.

$$\begin{aligned} \det(A) &= 0 \\ (2-s)(8-s) + 10 &= 0 \\ s^2 - 10s + 26 &= 0 \end{aligned}$$

$$\begin{aligned} \Delta &= (-10)^2 - 4(1)(26) \\ &= 100 - 104 \\ &= -4 \end{aligned}$$

$$s = (10 \pm \sqrt{-4})/2$$



What does $\sqrt{-4}$ mean?

Next week: complex numbers!