

Analysis 2

Tuesday, 14 May 2024

$$2e^{2t}\sin(t) + e^{2t}\cos(t)$$

Warm-up: (a) What is the derivative of $e^{2t}\sin(t)$?

(b) What is the derivative of $e^{-t}g(t)$?

$$-e^{-t}g(t) + e^{-t}g'(t)$$

Topics to review

Partial fractions.

- Example 1: $\frac{2x - 3}{x^2 - 5x - 6} = ?$

- Example 2: $\frac{25x}{(x^2 + 4)(x + 1)^2} = ?$

Integration by parts: $\int u dv = uv - \int v du.$

- Example: $\int t e^t dt = ?$

Topics to review

Partial fractions.

• Example 1: $\frac{2x - 3}{x^2 - 5x - 6} = \frac{9/7}{x - 6} + \frac{5/7}{x + 1}$

• Example 2: $\frac{25x}{(x^2 + 4)(x + 1)^2} = \frac{-3x + 8}{x^2 + 4} + \frac{3}{x + 1} + \frac{-5}{(x + 1)^2}$

Integration by parts: $\int u dv = uv - \int v du.$

• Example: $\int t e^t dt$. Choosing $u = t$ $v = e^t$
 $du = dt$ $dv = e^t dt$ gives

$$\int t e^t dt = t e^t - \int e^t dt = t e^t - e^t + C.$$

When the denominator has a repeated root, you need separate partial fractions for each power.

Separable ODE

Last
Time

A **separable** first-order ODE for $y(x)$ can be written in the form

$$\frac{dy}{dx} = f(x) \cdot g(y).$$

Its solution can usually be found using

$$\int \frac{1}{g(y)} dy = \int f(x) dx.$$

Whether these integrals are easy or not depends on g and f .

- Any **direct** first-order ODE is separable: $g(y) = 1$ gives $y' = f(x)$.
- Any **autonomous** first-order ODE is separable: $f(x) = 1$ gives $y' = g(y)$.

Linear ODE

In standard form, a **first-order linear ODE** for $y(t)$ is

$$y' + a(t)y = f(t).$$

In standard form, a **second-order linear ODE** for $y(t)$ is

$$y'' + a(t)y' + b(t)y = f(t).$$

In standard form, a **third-order linear ODE** for $y(t)$ is

$$y''' + a(t)y'' + b(t)y' + c(t)y = f(t).$$

- We could write $y(t)$, $y'(t)$, etc., instead of just y , y' .
Skipping some of the “ (t) ”s just makes the equation easier to read.
- We can use other letters: $x' + a(t)x = b(t)$ is a linear ODE for $x(t)$.

A first-order **linear** ODE for $y(x)$ can be written in the form

$$y' = P(x)y + Q(x)$$

for some functions $P(x)$ and $Q(x)$.

$$y' = xy + x^3 \text{ is}$$

linear

A first-order **linear** ODE for $y(x)$ can be written in the form

$$y' = P(x)y + Q(x)$$

for some functions $P(x)$ and $Q(x)$.

$$y' = xe^y + 5 \quad \text{is}$$

not linear

A first-order **linear** ODE for $y(x)$ can be written in the form

$$y' = P(x)y + Q(x)$$

for some functions $P(x)$ and $Q(x)$.

$$y' = e^x y$$

is

linear

and

separable

A first-order **linear** ODE for $y(x)$ can be written in the form

$$y' = P(x)y + Q(x)$$

for some functions $P(x)$ and $Q(x)$.

$$x' = P(t)x + Q(t)$$

$$x' = 3t^2x + 4 \text{ is}$$

linear

Linear ODE

In standard form, a **first-order linear ODE** for $y(t)$ is

$$y'(t) + a(t)y(t) = f(t).$$

- If both $a(t)$ and $f(t)$ are constant functions, then we have

$$y'(t) + a y(t) = b,$$

which is separable (in fact, autonomous), so we can already solve this.

- A **homogeneous** first-order linear ODE looks like

$$y'(t) + a(t)y(t) = 0.$$

This is also separable, so we can solve this too.

- The solution is $y = Ce^{-A(t)}$, where $A'(t) = a(t)$.

Monday	Tuesday	Wednesday	Thursday	Friday	Saturday	Sunday
13 May	14 May (today)	15 Problem Session Quiz 5	16	17	18 	19
20	21 Lecture	22 	23 	24	25 	26
27	28 Lecture	29 	30 	31 	1 June 	2
3	4 Lecture	5 Problem Session Quiz 6 ?	6	7	8 	9

First-order Linear

There are four tools we can (sometimes) use to solve **first-order linear** ODEs.

🤔 Laplace transforms

- variation of parameters
- integrating factor (next week)
- big formula (next week)

$$y' + a(t)y = f(t)$$

The idea of Laplace tr. is to change an IVP into an algebra problem (no analysis needed after that!). We usually use t as the variable in the ODE.

Laplace transforms

The idea of Laplace tr. is to change an IVP into an algebra problem (no analysis needed after that!). We usually use t as the variable in the ODE.

The **Laplace transform** of a function $f(t)$ is a new function $F(s)$ determined by the definition below. Notice that the variable changed from t to s . People sometimes say that formulas with t are in the “**time domain**” and formulas with s are in the “**frequency domain**”.

- Definition: $\mathcal{L}[f(t)] = \int_0^{\infty} f(t)e^{-st} dt$

- In practice, we can just use a table of common Laplace transforms.

Laplace transforms

Time	Frequency
e^{at}	$\frac{1}{s-a}$
$\sin(at)$	$\frac{a}{s^2+a^2}$
$\cos(at)$	$\frac{s}{s^2+a^2}$
t^n	$\frac{n!}{s^{n+1}}$

We write, for example,

$$\mathcal{L}[e^{2t}] = \frac{1}{s-2},$$

and say “the Laplace transform of e^{2t} is $\frac{1}{s-2}$ ”.

We can also go backwards: “the **inverse Laplace transform** of $\frac{24}{s^5}$ is t^4 ”, written as

$$\mathcal{L}^{-1}\left[\frac{24}{s^5}\right] = t^4.$$

Laplace transforms

Time	Frequency
e^{at}	$\frac{1}{s-a}$
$\sin(at)$	$\frac{a}{s^2+a^2}$
$\cos(at)$	$\frac{s}{s^2+a^2}$
t^n	$\frac{n!}{s^{n+1}}$

There are also some important properties of Laplace transforms:

- $\mathcal{L}[f(t) + g(t)] = F(s) + G(s)$.
- $\mathcal{L}[c \cdot f(t)] = c \cdot F(s)$.

Using the second bullet, the **inverse Laplace transform** of $\frac{8}{s^5}$ is

$$\mathcal{L}^{-1}\left[\frac{8}{s^5}\right] = \mathcal{L}^{-1}\left[\frac{1}{3} \cdot \frac{24}{s^5}\right] = \frac{1}{3}t^4.$$

Laplace transforms

Time	Frequency
e^{at}	$\frac{1}{s-a}$
$\sin(at)$	$\frac{a}{s^2+a^2}$
$\cos(at)$	$\frac{s}{s^2+a^2}$
t^n	$\frac{n!}{s^{n+1}}$
$y'(t)$	$sY(s) - y(0)$

There are also some important properties of Laplace transforms:

- $\mathcal{L}[f(t) + g(t)] = F(s) + G(s).$
- $\mathcal{L}[c \cdot f(t)] = c \cdot F(s).$
- $\mathcal{L}[e^{at}f(t)] = F(s - a).$
- $\mathcal{L}[tf(t)] = -F'(s).$
- $\mathcal{L}[f'(t)] = sF(s) - f(0).$

This last one uses both F and f . It is also why we can use \mathcal{L} to solve ODEs!

Note: there is no nice formula for $\mathcal{L}[f(t)g(t)].$

Example: Solve $y' + y = t$, $y(0) = 8$ using Laplace transf.

$$\mathcal{L}[y'] + \mathcal{L}[y] = \mathcal{L}[t]$$

$$sY - 8 + Y = \frac{1}{s^2}$$

$$Y = \frac{1+8s^2}{s^2+s+1} = \frac{9}{s+1} + \frac{-1}{s} + \frac{1}{s^2} \quad (\text{partial fractions!})$$

$$y = 9 \mathcal{L}^{-1} \left[\frac{1}{s+1} \right] - \mathcal{L}^{-1} \left[\frac{1}{s} \right] + \mathcal{L}^{-1} \left[\frac{1}{s^2} \right]$$

$$y = 9e^{-t} - 1 + t$$

Time	Frequency
e^{at}	$\frac{1}{s-a}$
t^n	$\frac{n!}{s^{n+1}}$
$y'(t)$	$sY(s) - y(0)$

First-order Linear

There are four tools we can (sometimes) use to solve **first-order linear** ODEs.

- Laplace transforms
- 🤔 variation of parameters
- integrating factor (next week)
- big formula (next week)

$$y' + a(t)y = f(t)$$

The solution to the similar ODE

$$y' + a(t)y = 0$$

is just $y = Ce^{-A(t)}$, where $A' = a$.

What if instead of a constant C we used $y = g(t)e^{-A(t)}$ for some $g(t)$?

Example: Solve $y' + y = t$ using variation of parameters.

Because $y' + y = 0$ has solution $y = C \cdot e^{-t}$,
assume that $y(t) = g(t) \cdot e^{-t}$ for some function g .

The ODE is $y' + y = t$, so we need to use

$$(ge^{-t})' + ge^{-t} = t$$

Warm-up: (a) What is the derivative of $e^{2t} \sin(t)$?

(b) What is the derivative of $e^{-t}g(t)$?

$$-e^{-t}g(t) + e^{-t}g'(t)$$

Example: Solve $y' + y = t$ using variation of parameters.

Because $y' + y = 0$ has solution $y = C \cdot e^{-t}$,
assume that $y(t) = g(t) \cdot e^{-t}$ for some function g .

The ODE is $y' + y = t$, so we need to use

$$(g \cdot (-e^{-t}) + g' \cdot e^{-t}) + g e^{-t} = t \quad \text{from warm-up}$$

...

...

$$g = t e^t - e^t + C$$

$$\text{Finally, } y = g e^{-t} = (t e^t - e^t + C) e^{-t} = \boxed{t - 1 + C e^{-t}}$$

First-order Linear

There are four tools we can (sometimes) use to solve **first-order linear** ODEs.

- Laplace transforms
- variation of parameters
- integrating factor (next week)
- big formula (next week)

$$y' + a(t)y = f(t)$$