### 25 November 2021

Warm-up: Vector subtraction, perpendicular vectors, parallel vectors.



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The word "vector" can mean many things. At times we will think of a vector as

- a point.
- an arrow with its tail at the origin.
- an arrow with its tail anywhere.

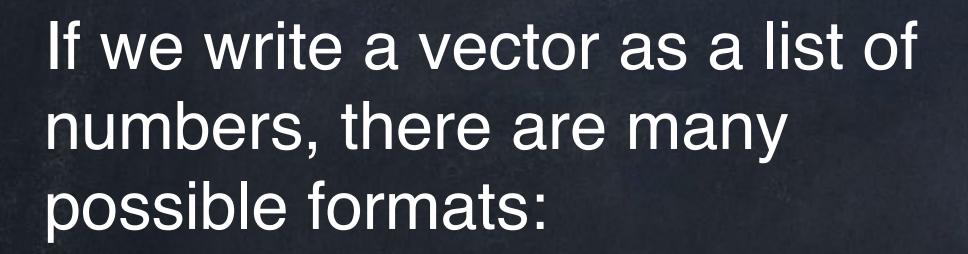
There is another option,

an element of an abstract vector space, but we won't use that idea of a vector in this class.





### Vector variables can be written with an arrow above the letter.





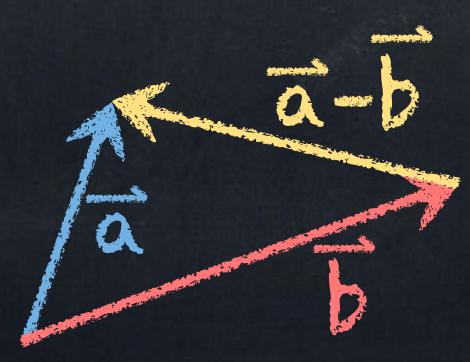


Special vectors in 2D:  $\stackrel{\rightarrow}{0} = [0, 0]$  is "the zero vector"  $\circ \vec{\iota} = [1,0]$  $\vec{j} = [0, 1]$ Special vectors in 3D:  $\stackrel{\rightarrow}{0} = [0, 0, 0]$  is "the zero vector"  $\circ \vec{i} = [1, 0, 0]$  $\vec{j} = [0, 1, 0]$  $\vec{k} = [0, 0, 1]$ 

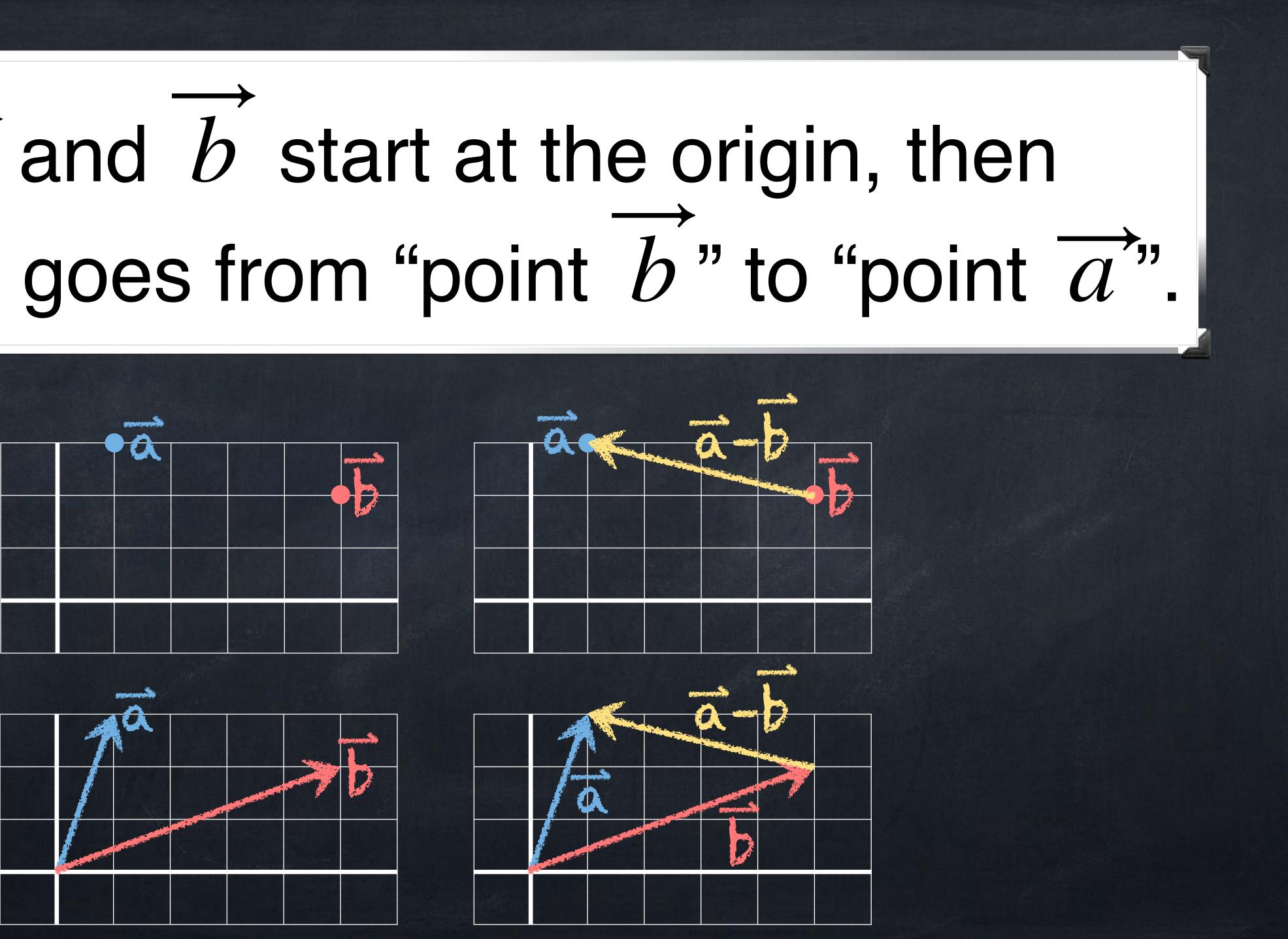


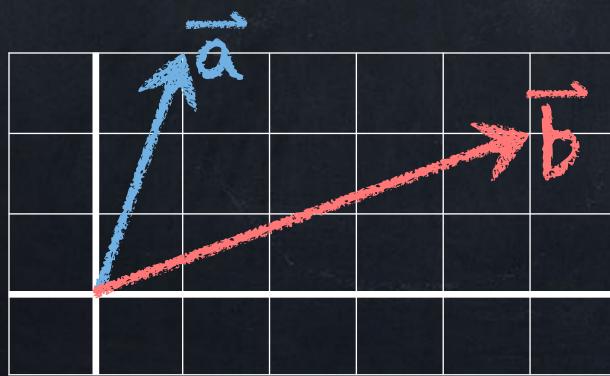
### In terms of arrows, we have "tip-to-tail addition". Example: 0

# If $\overrightarrow{a}$ , $\overrightarrow{b}$ start at the same point, then $\overrightarrow{a} - \overrightarrow{b}$ points from the end of $\overrightarrow{b}$ to the end of $\overrightarrow{a}$ . Example:



# If $\overrightarrow{a}$ and $\overrightarrow{b}$ start at the origin, then $\overrightarrow{a} - \overrightarrow{b}$ goes from "point $\overrightarrow{b}$ " to "point $\overrightarrow{a}$ ".





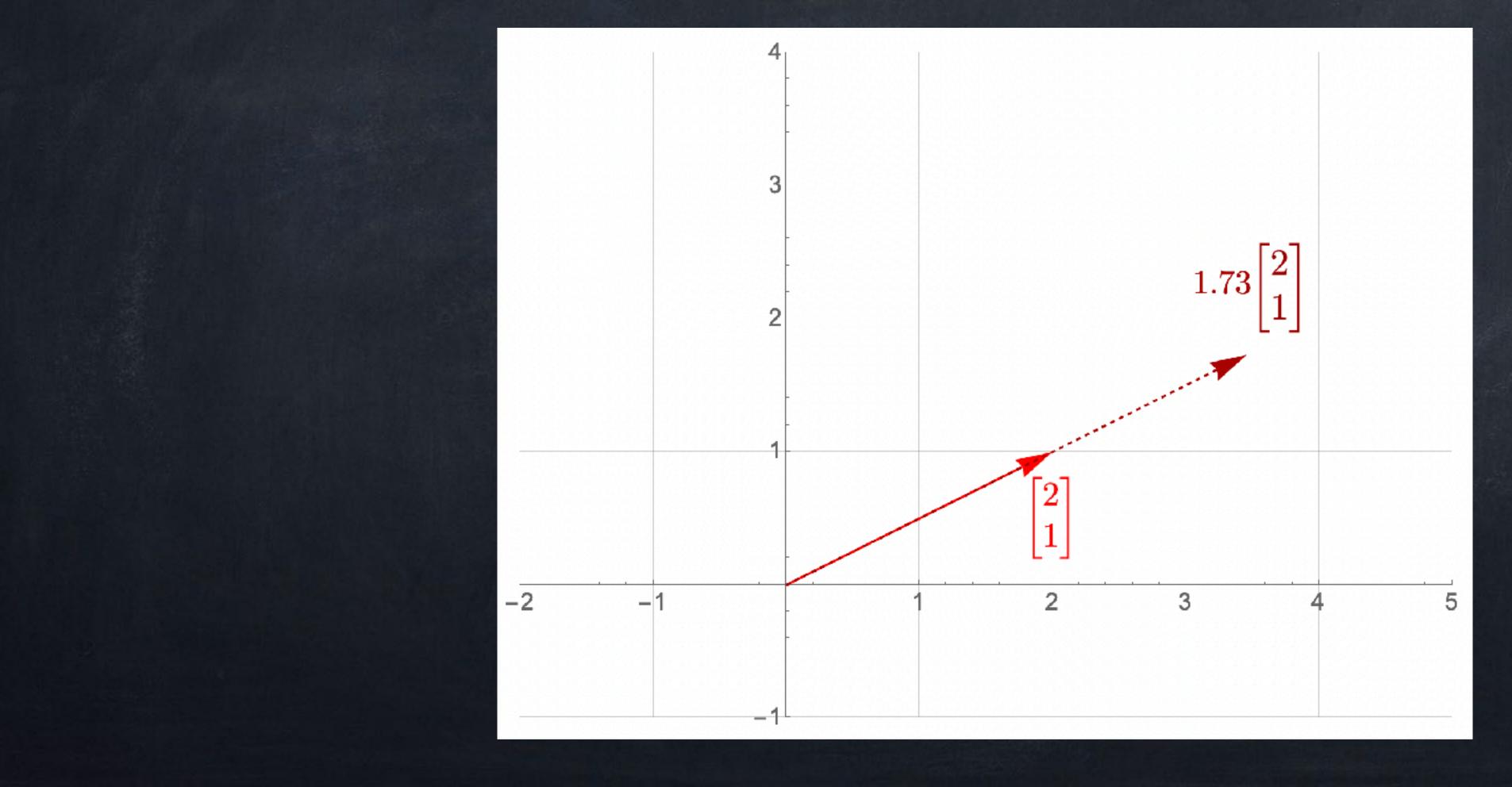
# Last week: mailiplication We will *never* combine $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$ into $\begin{bmatrix} (1)(4) \\ (2)(5) \\ (3)(6) \end{bmatrix} = \begin{bmatrix} 4 \\ 10 \\ 18 \end{bmatrix}$ in this class.

Instead we have

• scalar multiplication 7  $\begin{vmatrix} 1 \\ 2 \\ 3 \end{vmatrix} = \begin{vmatrix} (7)(1) \\ (7)(2) \\ (7)(3) \end{vmatrix} = \begin{vmatrix} 7 \\ 14 \\ 21 \end{vmatrix}$ • dot product  $\begin{vmatrix} 1 \\ 2 \\ 3 \end{vmatrix} \cdot \begin{vmatrix} 4 \\ 5 \\ 6 \end{vmatrix} = (1)(4) + (2)(5) + (3)(6) = 32$ • cross product  $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \times \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \\ -3 \end{bmatrix}$  to be explained later



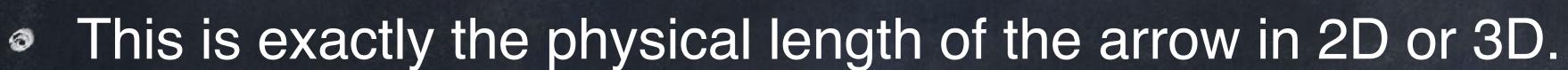
## A scalar multiple of an arrow is a stretched (scaled) version—the magnitude can change, but the direction does not.



# Last week: multiplication



### The magnitude (or length or norm) of the vector $\vec{v}$ is written $|\vec{v}|$ .



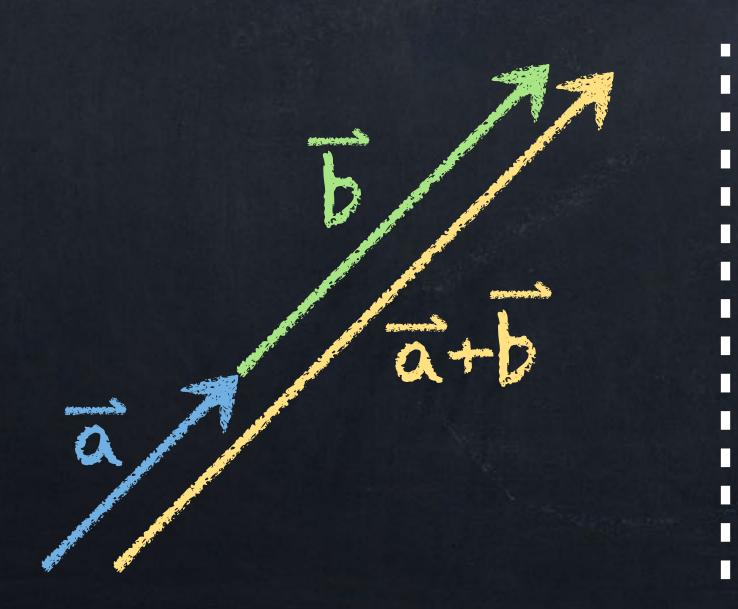
A vector with magnitude 1 is called a unit vector.

Some people use a hat when writing unit vectors:  $\hat{u} = \begin{bmatrix} 3/5 \\ 1/2 \end{bmatrix}$ 

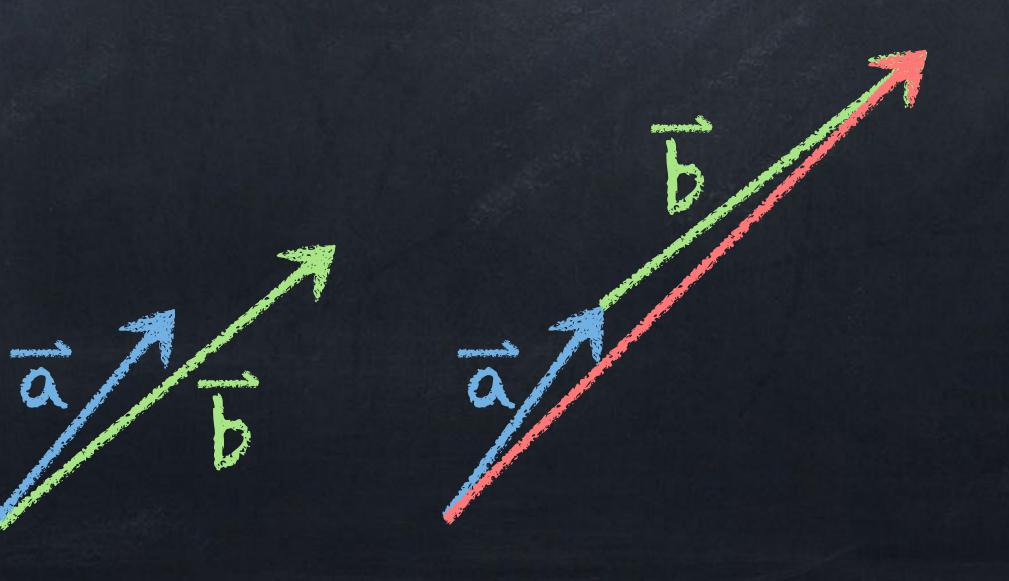
For 
$$\overrightarrow{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$
, we have  $|\overrightarrow{v}| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$ .

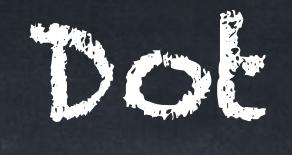
4/5

# $\begin{vmatrix} \overrightarrow{a} \\ \overrightarrow{a} \end{vmatrix} \ge 0. \qquad \qquad \begin{vmatrix} \overrightarrow{a} \\ \overrightarrow{a} \end{vmatrix} = 0 \text{ if and only if } \overrightarrow{a} = \overrightarrow{0}.$ $\begin{vmatrix} \overrightarrow{s} \\ \overrightarrow{a} \end{vmatrix} = |s| |\overrightarrow{a}|.$ $\begin{vmatrix} \overrightarrow{a} + \overrightarrow{b} \end{vmatrix} \le |\overrightarrow{a}| + |\overrightarrow{b}|. \text{ This is called the "Triangle Inequality".}$











# The **dot product** of two vectors $\vec{a} = \begin{vmatrix} a_1 \\ a_2 \end{vmatrix}$ and $\vec{b} = \begin{vmatrix} b_1 \\ b_2 \end{vmatrix}$ , which

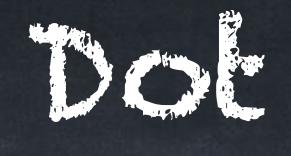
we write as  $\vec{a} \cdot \vec{b}$  (said aloud as "A dot B"), is a number that can be computed as either

•  $\overrightarrow{a} \cdot \overrightarrow{b} = a_1b_1 + a_2b_2$ 

or

•  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\text{angle between } \vec{a} \text{ and } \vec{b}).$ 







we write as  $\vec{a} \cdot \vec{b}$  (said aloud as "A dot B"), is a number that can be computed as either

 $\overrightarrow{a} \cdot \overrightarrow{b} = a_1b_1 + a_2b_2 + a_3b_3$ 

or

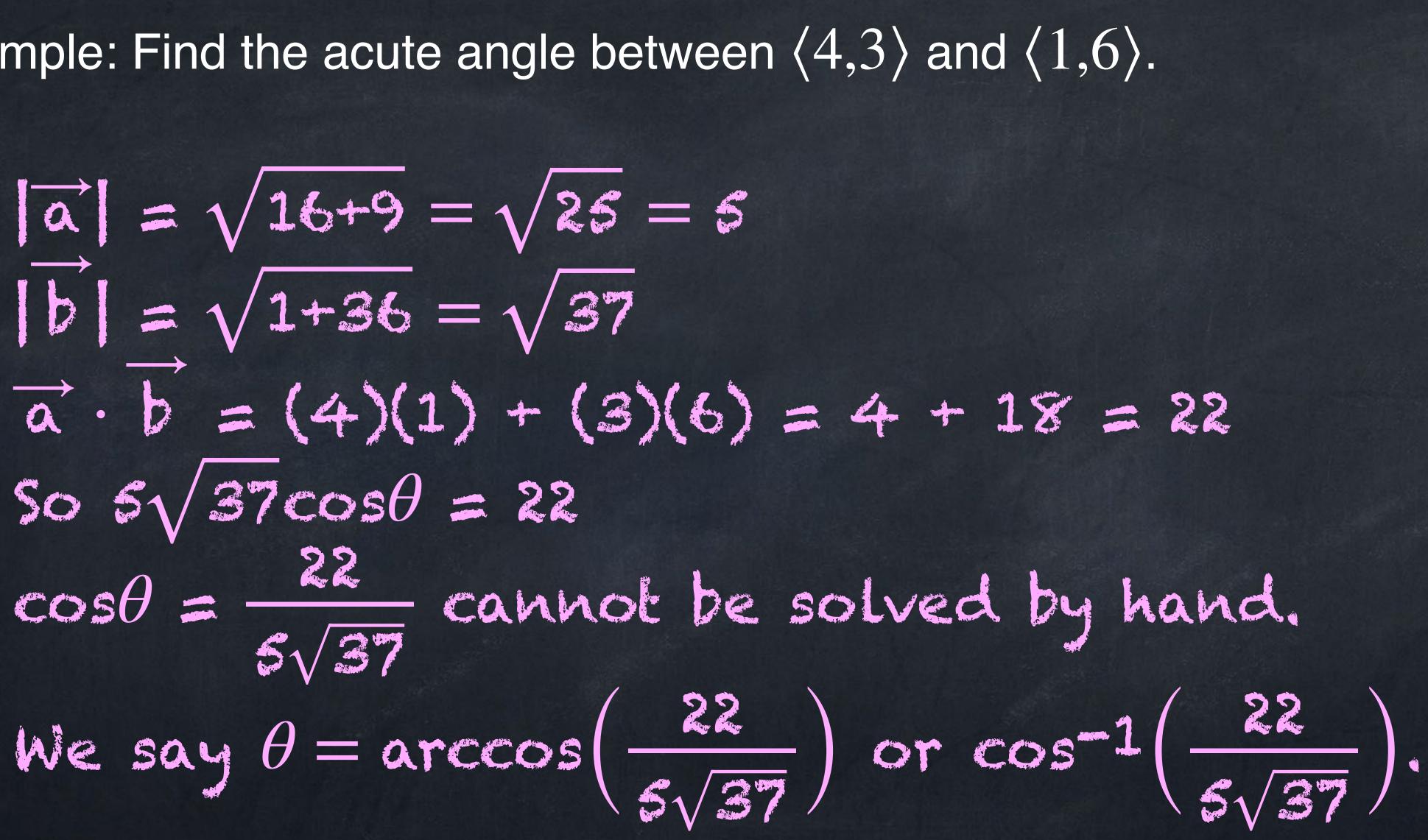
•  $\vec{a} \cdot \vec{b} = \left| \vec{a} \right| \left| \vec{b} \right| \cos(\text{angle between } \vec{a} \text{ and } \vec{b}).$ 



# The **dot product** of two vectors $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ , which

### Example: Find the acute angle between $\langle 4,3 \rangle$ and $\langle 1,6 \rangle$ .

 $|\overrightarrow{a}| = \sqrt{16+9} = \sqrt{25} = 5$  $\vec{b} = \sqrt{1+36} = \sqrt{37}$  $\vec{a} \cdot \vec{b} = (4)(1) + (3)(6) = 4 + 18 = 22$  $50 6\sqrt{37}\cos\theta = 22$ 



Two vectors are called orthogonal if their dot product is zero. For non-zero vectors, this means they are perpendicular (or normal). Since  $\vec{u} \neq 0$  and  $\vec{v} \neq 0$ ,  $|\vec{u}|$  and  $|\vec{v}|$  cannot be 0. So  $\cos\theta$ 

The zero vector is orthogonal to every vector:

# Orthogonal / perpendicular Why? Using the second dot prod. formula, $\vec{u} \cdot \vec{v} = 0$ means $|\overrightarrow{u}||\overrightarrow{v}|\cos\theta=0.$

must be 0, and for an acute angle this means  $\theta$  must be 90°.

 $0 \cdot \langle v_1, v_2, ..., v_n \rangle = 0v_1 + 0v_2 + ... + 0v_n$ = 0 + 0 + ... + 0 = 0

# Which of $\overrightarrow{a} = [4, 2]$ or $\overrightarrow{b} = [4, 3]$ is orthogonal to [2, -4]?

 $\overrightarrow{a}$ 

Any non-zero scalar multiple of [7, -3]. These include [7, -3] and [14, -6] and [-7, 3] and [-3.5, -1.5].

Give an example of a non-zero vector that is orthogonal to  $\vec{c} = [3, 7]$ .



- for sets we use capital letters.
  - Example:  $S = \{1, 2, 3, 25, 1000\}.$
- Order doesn't matter.
  - $\{38, 4, -5\}$  is exactly the same set as  $\{-5, 38, 4\}$ .

Some collections have their own special symbols: The collection of all natural numbers is written as  $\mathbb{N}$  or  $\mathbb{N}$ . 0 • The collection of all real numbers is written as  $\mathbb{R}$  or  $\mathbb{R}$ . • 3D space is  $\mathbb{R}^3$ .

- The 2D plane is  $\mathbb{R}^2$ .

# 

In mathematics it is often useful to talk about a set (or collection) of objects. Usually a set is written using curly brackets { }, and when we use a variable



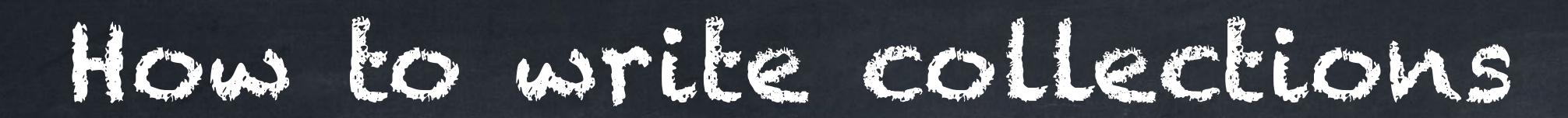
- The symbol  $\in$  means "is an element of" (or "is in"). 0
- For example since  $\mathbb{R}$  is the collection of all real numbers,

number".

- More examples:
  - " $k \in \mathbb{N}$ " mean "k is a natural number".
  - " $t \in \mathbb{R}$ " means "t is a real number".
  - " $\vec{u} \in \mathbb{R}^3$ " means " $\vec{u}$  is in 3D space".

 $x \in \mathbb{R}$ means "x is in the collection of real numbers", which is the same as "x is a real





# Instead of listing items, we often describe collections by some rules.

brackets

colon

kind of object (number, vector, etc.)

The following are different ways to write exactly the same statement: •  $S = \{1, 3, 5, 7, 9, ...\}$ 

- $S = \{x : x \text{ is an odd natural number}\}$
- $S = \{n \in \mathbb{N} : n \text{ is odd}\}$
- $S = \{2k+1 : k \in \mathbb{N}\}$

brackets

rules / requirements / descriptions

Remember  $\in$  means "is in".



The objects in a collection do not have to be numbers. Examples:

- $A = \{\langle 4,3 \rangle, \langle 2,-5 \rangle, \langle 1,31 \rangle, \langle -5,9 \rangle\}$  is a set of four vectors.
- $B = \{5, 9, 3, 8, 7\}$  is a collection of 5 numbers.
- $D = \{5t : t \in \mathbb{R}\}$  is exactly the collection  $\mathbb{R}$ .
- $E = \{\langle 4t, 10t \rangle : t \in \mathbb{R}\}$  is a collection of vectors that

•  $C = \{5t : t \in \mathbb{N}\}$  is a set of infinitely many numbers (5, 10, 15, ...).

includes  $\langle 4,10\rangle$  and  $\langle 2,5\rangle$  and  $\langle -4,-10\rangle$  (but not  $\langle 4,0\rangle$ ).



# The objects in a collection do not have to be numbers. Examples:

•  $A = \left\{ \begin{bmatrix} 4 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ -5 \end{bmatrix}, \begin{bmatrix} 1 \\ 31 \end{bmatrix}, \begin{bmatrix} -5 \\ 9 \end{bmatrix} \right\}$  is a set of four vectors. •  $B = \{5, 9, 3, 8, 7\}$  is a collection of 5 numbers. •  $D = \{5t : t \in \mathbb{R}\}$  is exactly the collection  $\mathbb{R}$ . •  $E = \left\{ \begin{bmatrix} 4t \\ 10t \end{bmatrix} : t \in \mathbb{R} \right\}$  is a collection of vectors that includes  $\begin{bmatrix} 4 \\ 10 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ 5 \end{bmatrix}$  and  $\begin{bmatrix} -4 \\ -10 \end{bmatrix}$  (but not  $\begin{bmatrix} 4 \\ 0 \end{bmatrix}$ ).

•  $C = \{5t : t \in \mathbb{N}\}$  is a set of infinitely many numbers (5, 10, 15, ...).



# You will need to be able to work *both* visually *and* with equations/symbols about

Iines in 2D

Iines in 3D

### planes in 3D

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