Warm-up: Subtraction, dot product, perpendicular vectors.

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A direction vector for a line is a vector that is parallel to the line.

If we know a point on a line L and a direction vector for a line L, 0 then there is exactly one line L that fits both of these.

> The line through the point  $\overrightarrow{p}$  with direction vector  $\overrightarrow{d}$ has equation

in 2D or 3D!



$$\overrightarrow{p} + t \overrightarrow{d}$$





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## The line in 2D through the point $(x_0, y_0)$ with direction vector $\vec{d} = [a, b]$ has parametric equations $x = x_0 + at$ $y = y_0 + bt$

# vector $\vec{d} = [a, b, c]$ has parametric equations



The line in 3D through the point  $(x_0, y_0, z_0)$  with direction  $x = x_0 + at$  $y = y_0 + bt$  $z = z_0 + ct$ 

is parallel to the line

 $L_{2}: x = 4 + 2t,$ 

The direction vector for L2 is [2,4,-1] (because this is what is multiplied by t). That vector is parallel to  $L_2$ , and we want  $L_1$  to be parallel to  $L_2$ , so we want [2,4,-1] to be parallel to  $L_1$ .

$$x = 6 + 2k$$
  
or  $y = 2 + 4k$   
 $z = 1 - k$ 

Give an equation for the line  $L_1$  that goes through the point (6, 2, 1) and

$$y = -1 + 4t, z = 5 - t$$



Line through point  $\overrightarrow{p}$  with direction vector  $\overrightarrow{d}$  has equation  $\vec{r} = \vec{p} + t d$ .





parameters.

Example: The plane through ( – has parametric equations  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -2 \\ 7 \\ 6 \end{bmatrix}$ 

which we can also write as



### It is possible to make parametric equations for planes, but it requires two

2,7,6) parallel to both 
$$\begin{bmatrix} 1\\4\\10 \end{bmatrix}$$
 and  $\begin{bmatrix} 3\\3\\7 \end{bmatrix}$   
+  $t \begin{bmatrix} 1\\4\\10 \end{bmatrix} + s \begin{bmatrix} 3\\3\\7 \end{bmatrix}$ ,

x = -2 + t + 3sy = 7 + 4t + 3s. z = 6 + 10t + 7s

 $\begin{bmatrix} 2 \end{bmatrix}$ 



parameters.

### It is possible to make parametric equations for planes, but it requires two

## However, an equation with only x, y, z (no t or s) will actually be simpler.



If we know

a point on a plane P and 0 a normal vector for a plane P, 0 then there is exactly one plane P that fits both of these.



### A normal vector for a plane is a vector that is perpendicular to the plane.

## The plane through (0,0,0) with normal vector [3, 1, 5] looks like



IF the point (-1, 2, 8) is on the plane through (0, 0, 0) with normal vector [3, 1, 5] then

- the arrow from (0,0,0) to (-1,2,8) is perpendicular to [3,1,5].
- the vector [-1, 2, 8] is perpendicular to [3, 1, 5].
- the dot product  $[3, 1, 5] \cdot [-1, 2, 8]$  equals 0.
- 3(-1) + 1(2) + 5(8) = 0.
- $a_{39} = 0.$

So we know that (-1, 2, 8) is *not* on this plane.

Is (-1, 2, 8) is on the plane through the origin with normal vector [3, 1, 5]?

IF the point (4, -7, -1) is on the plane through (0, 0, 0) with normal vector [3, 1, 5] then

- the vector [4, -7, -1] is perpendicular to [3, 1, 5].
- the dot product  $[3, 1, 5] \cdot [4, -7, -1]$  equals 0.
- 3(4) + 1(-7) + 5(-1) = 0.
- $\circ$  0 = 0.

So we know that (4, -7, -1) is on this plane.

• the arrow from (0,0,0) to (4, -7, -1) is perpendicular to [3, 1, 5].

If the point (x, y, z) is on the plane through (0,0,0) with normal vector [3, 1, 5] then

• the arrow from (0,0,0) to (x, y, z) is perpendicular to [3, 1, 5].

- the vector [x, y, z] is perpendicular to [3, 1, 5].
- the dot product  $[3, 1, 5] \cdot [x, y, z]$  equals 0.
- 3x + y + 5z = 0.

So "3x + y + 5z = 0" is the equation for the plane through the origin normal to [3, 1, 5]!

> The plane in 3D through (0, 0, 0) with normal vector  $\vec{n}$ has equation n

If n is [a,b,c], this equ is axt

## $\vec{r}$ means

$$\cdot \vec{r} = 0.$$



## What if the plane does not go through (0, 0, 0)?

Is (-9, 8, 2) is on the plane through (4, 1, 1) with  $\vec{n} = [3, 1, 5]$ ? *IF* it is, then

- the arrow from (4, 1, 1) to (-9, 8, 2) is perpendicular to [3, 1, 5].

- 3(-9 4) + 1(8 1) + 5(2 1) = 0.

• the vector ([-9, 8, 2] - [4, 1, 1]) is perpendicular to [3, 1, 5]. • the dot product  $[3, 1, 5] \cdot ([-9, 8, 2] - [4, 1, 1])$  equals 0.

## What if the plane does not go through (0, 0, 0)?

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## What if the plane does not go through (0, 0, 0)?

- Is (x, y, z) is on the plane through (4, 1, 1) with  $\vec{n} = [3, 1, 5]$ ? *IF* it is, then
- the arrow from (4, 1, 1) to (x, y, z) is perpendicular to [3, 1, 5].
- the vector ([x, y, z] [4, 1, 1]) is perpendicular to [3, 1, 5].
- 3(x 4) + 1(y 1) + 5(z 1) = 0.

• the dot product  $[3, 1, 5] \cdot ([x, y, z] - [4, 1, 1])$  equals 0.



## A normal vector for a plane is a vector that is perpendicular to the plane.







## Give an equation *without vectors* for the plane through (12, 4, -3) normal to [-2, 8, 8].

## Wilhoul vectors,





-2(x - 12) + 8(y - 4) + 8(z + 3) = 0-2x + 8y + 8z = -16x - 44 - 42 = X

The direction vector for the line is [10,1,-2].

That vector is parallel to the line, and the line is perpendicular to our plane, so we can use [10,1,-2] as the normal vector for our plane.

Give an equation for the plane through the origin perpendicular to the line L:  $\vec{r} = \begin{bmatrix} -2 + 10t \\ 9 + t \\ -4 - 2t \end{bmatrix}$ .

 $[10,1,-2] \cdot \vec{r} = 0$  or 10x + y - 2z = 0

# (-2, 7, 6) parallel to both [1, 4, 10] and [3, 3, 7], we would need $\circ$ a point on the plane use (-2, 7, 6)a normal vector for the plane.

If we wanted an equation x + y + z = z for the plane through

• This vector will be perpendicular to both [1, 4, 10] and [3, 3, 7].



the vector that is

perpendicular to both  $\overrightarrow{a}$  and  $\overrightarrow{b}$  and • has length  $\left| \overrightarrow{a} \right| \left| \overrightarrow{b} \right|$  sin(angle between  $\overrightarrow{a}$  and  $\overrightarrow{b}$ ) and follows the "Right-Hand Rule". 0 The formula is ugly:

 $\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \times \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{bmatrix}.$ 

## For 3D vectors only, the cross product of $\vec{a}$ and $\vec{b}$ , written $\vec{a} \times \vec{b}$ , is

Cross Products



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## Lincar compinations

A linear combination of some vectors is any sum of scalar multiples of those vectors. In symbols,  $\overrightarrow{u}$  is a linear combination of  $\overrightarrow{v}$  and  $\overrightarrow{w}$  if  $\overrightarrow{u} = \overrightarrow{sv} + t\overrightarrow{w}$ 

for some numbers s, t.

• For more vectors,  $\vec{u}$  is a linear combination of  $\vec{v_1}, \vec{v_2}, \ldots, \vec{v_n}$  if for some numbers  $S_1, \ldots, S_n$ .

 $\overrightarrow{u} = s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \dots + s_n \overrightarrow{v_n}$ 

# Linear compinations

A linear combination of some vectors is any sum of scalar multiples of those vectors. In symbols,  $\vec{u}$  is a linear combination of  $\vec{v}$  and  $\vec{w}$  if

for some numbers s, t.

 $s\begin{bmatrix}1\\4\end{bmatrix} + t\begin{bmatrix}0\\8\end{bmatrix} = \begin{bmatrix}s\\4s+8t\end{bmatrix}$ . For this to equal  $\begin{bmatrix}s\\24\end{bmatrix}$  we need s = 5. Then 4(5) + 8t = 24, so 8t = 4, so t = 1/2.

 $\vec{u} = \vec{s} \cdot \vec{v} + t \cdot \vec{w}$ 

Example 1: Write  $\begin{vmatrix} 5 \\ 24 \end{vmatrix}$  as a linear combination of  $\vec{v_1} = \begin{vmatrix} 1 \\ 4 \end{vmatrix}$  and  $\vec{v_2} = \begin{vmatrix} 0 \\ 8 \end{vmatrix}$ .



# Example 2: $\begin{vmatrix} 5 \\ 24 \end{vmatrix}$ *cannot* be written as a linear combination of $\vec{v}_1 = \begin{vmatrix} 5 \\ 1 \end{vmatrix}$ and $\overrightarrow{v_2} = \begin{bmatrix} 10\\2 \end{bmatrix}$ . Why?

# Using equations: $s\begin{bmatrix}5\\1\end{bmatrix} + t\begin{bmatrix}10\\2\end{bmatrix} = \begin{bmatrix}5s+10t\\s+2t\end{bmatrix} = \begin{bmatrix}5(s+2t)\\s+2t\end{bmatrix} = (s+2t)\begin{bmatrix}5\\1\end{bmatrix}$

To get "n = 5" would require n=1 and n=3at the same, which is impossible.



The "span" of  $\vec{\mathbf{v}}$  and  $\vec{\mathbf{w}}$  is the set of all their linear combinations.

## $a\vec{\mathbf{v}}+b\vec{\mathbf{w}}$

## Let a and b vary over all real numbers

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the vectors.

For two vectors,

# Earlier we saw that $\begin{bmatrix} 5\\24 \end{bmatrix}$ cannot be written as a linear combination of $\begin{bmatrix} 5\\1 \end{bmatrix}$ and $\begin{bmatrix} 10\\2 \end{bmatrix}$ . We can say " $\begin{bmatrix} 5\\24 \end{bmatrix}$ is not in the span of $\begin{bmatrix} 5\\1 \end{bmatrix}$ and $\begin{bmatrix} 10\\2 \end{bmatrix}$ ."



## The span of some vectors is the collection of all linear combinations of

## $\operatorname{span}(\overrightarrow{v}, \overrightarrow{w}) = \left\{ s\overrightarrow{v} + t\overrightarrow{w} : s, t \in \mathbb{R} \right\}$



The span of some vectors is the collection of all linear combinations of the vectors. For two vectors,  $\operatorname{span}(\overrightarrow{v}, \overrightarrow{w}) = \{ \overrightarrow{sv} + t\overrightarrow{w} : s, t \in \mathbb{R} \}$ is usually a plane, but it might be a line or just the origin. For three vectors, what shape is  $\operatorname{span}(\overrightarrow{u},\overrightarrow{v},\overrightarrow{w}) = \{\overrightarrow{ru} + \overrightarrow{sv} + t\overrightarrow{w} : r, s, t \in \mathbb{R}\}?$ If  $\overrightarrow{u}$ , ... are 2D vectors, this can still be only a point, line, or plane. • If  $\vec{u}, \ldots$  are 3D vectors, this can be a point, line, plane, or 3D space.

